

From the Hartree–Fock dynamics to the Vlasov equation

Chiara Saffirio

Universität Zürich

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Solution $\psi_{N,t} = e^{-iH_N t} \psi_N$, but N is huge \implies look for scaling regimes in which the evolution can be well approx. by an **effective dynamics**.

Fermionic mean-field scaling

Fix λ such that interaction and kinetic energy are of the same order:

$$E_{\text{int}} = \langle \psi_N, \lambda \sum_{i < j}^N V(x_i - x_j) \psi_N \rangle \sim \lambda N^2$$

$$E_{\text{kin}} = \langle \psi_N, \sum_{j=1}^N -\Delta_{x_j} \psi_N \rangle \sim N^{5/3}$$

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Relevant time scale: $N^{-1/3}$ (typical velocity per particle $\sim N^{1/3}$).

Rescaling time

$$iN^{1/3} \partial_t \psi_{N,t} = \left(\sum_{j=1}^N -\Delta_{x_j} + N^{-1/3} \sum_{i < j}^N V(x_i - x_j) \right) \psi_{N,t}.$$

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$$\varepsilon = N^{-1/3}$$

and multiplying by ε^2 :

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The mean-field scaling is naturally linked with a **semiclassical limit**

Effective equations

Let $\gamma_{N,t}^{(1)} = N \operatorname{tr} |\psi_{N,t}\rangle\langle\psi_{N,t}|$ be the one-particle density matrix of $\psi_{N,t}$.

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$$\gamma_{N,0}^{(1)} \simeq \omega_N \text{ (minimiser of the Hartree-Fock energy functional)}$$

$$\Downarrow N \gg 1$$

$$\gamma_{N,t}^{(1)} \simeq \omega_{N,t}, \text{ solution of the } \mathbf{Hartree-Fock equation}$$

$$i\epsilon\partial_t\omega_{N,t} = [-\epsilon^2\Delta + V * \rho_t - X_t, \omega_{N,t}],$$

where $\rho_t(x) := \frac{1}{N}\omega_{N,t}(x; x)$ and $X_t(x; y) = \frac{1}{N}V(x-y)\omega_{N,t}(x; y)$.

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The Wigner transform of $\omega_{N,t}$

$$W_{N,t}(x, v) = \frac{\epsilon^3}{(2\pi)^3} \int dy \omega_{N,t}(x + \epsilon \frac{y}{2}; x - \epsilon \frac{y}{2}) e^{-iv \cdot y}$$

for $N \rightarrow \infty$ solves the Vlasov equation

$$\partial_t W_t(x, v) + v \cdot \nabla_x W_t(x, v) = \nabla(V * \rho_t)(x) \cdot \nabla_v W_t(x, v)$$

Known results

★ MBQ dynamics \rightarrow Vlasov:

Narnhofer and Sewell (1981), Spohn (1981).

★ MBQ dynamics \rightarrow Hartree or Hartree–Fock:

- ▶ Elgart, Erdös, Schlein, Yau (2004): mean–field + semiclassical scaling; analytic V , short times.
- ▶ Benedikter, Porta and Schlein (2013): weaker assumption on V , effective estimate on the rate of convergence $\forall t$, zero temperature.
- ▶ Petrat, Pickl (2014): similar result with a different method.
- ▶ Benedikter, Porta, Jakšić, S. and Schlein (2015): positive temperature.

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- ▶ Golse, Paul (2015) ∇V Lipschitz continuous, explicit estimates on the rate of convergence.

Notations

ω_N sequence of reduced densities on $L^2(\mathbb{R}^3)$

$$\text{tr } \omega_N = N, \quad 0 \leq \omega_N \leq 1$$



Wigner trans.

W_N

Vlasov eq.n

$\tilde{W}_{N,t}$

Weyl quantization

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$$i \varepsilon \partial_t \omega_{N,t} = [h(t), \omega_{N,t}]$$

$$h(t) = -\varepsilon^2 \Delta + V * \rho_t$$

$$i \varepsilon \partial_t \tilde{\omega}_{N,t} = [-\varepsilon^2 \Delta, \tilde{\omega}_{N,t}] + A_t$$

$$A_t(x; y) = \nabla(V * \tilde{\rho}_t) \left(\frac{x+y}{2} \right) \cdot (x-y) \tilde{\omega}_{N,t}(x; y)$$

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$$\begin{aligned}\| [x, \omega_N] \|_{\text{HS}}^2 &= \int dx dy |(x-y) \omega_N(x; y)|^2 \\ &= \int dx dy \left| N \int dv (x-y) W_N\left(\frac{x+y}{2}, v\right) e^{iv \cdot \frac{(x-y)}{\varepsilon}} \right|^2 \\ &= \int dx dy N^2 \left| \int dv \varepsilon \nabla_v W_N\left(\frac{x+y}{2}, v\right) e^{iv \cdot \frac{(x-y)}{\varepsilon}} \right|^2 \\ &= \int dR dr \cancel{N} N \left| \int dv \varepsilon \nabla_v W_N(R, v) e^{iv \cdot r} \right|^2 \\ &= N \varepsilon^2 \|\nabla_v W_N\|_{L^2_{x,v}}^2\end{aligned}$$

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- $\|W_N\|_{H_a^s}^2 = \sum_{\beta \leq s} \int (1+x^2+v^2)^a |\nabla^\beta W_N(x, v)|^2 dx dv$

Statement of the results: mixed states

Theorem 1 (Benedikter, Porta, S., Schlein)

Let $V \in \mathcal{W}^{2,\infty}(\mathbb{R}^3)$ and $\|W_N\|_{H_4^5} < C$.

Then there exists $C = C(\|V\|_{\mathcal{W}^{2,\infty}}, \sup_N \|W_N\|_{H_4^2}) > 0$ such that

$$\mathrm{tr} |\omega_{N,t} - \tilde{\omega}_{N,t}| \leq CN\varepsilon \exp(C \exp(C|t|)) \left[1 + \sum_{k=1}^3 \varepsilon^k \sup_N \|W_N\|_{H_4^{k+2}} \right].$$

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Theorem 2 (Benedikter, Porta, S., Schlein)

Let $V \in L^1(\mathbb{R}^3)$ such that $A = \int |\hat{V}(p)| (1 + |p|^2) dp < \infty$ and $\|W_N\|_{H_4^2} < C$.

Then there exists $C = C(\|W_N\|_{H_4^2}, A) > 0$ such that

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Equivalently,

$$\|W_{N,t} - \tilde{W}_{N,t}\|_{L^2} \leq C\varepsilon \exp(C \exp(C|t|)).$$

Statement of the results: pure states

At zero temperature we prove convergence for the expectation of a class of **semiclassical observables**, functions of x and $-i\varepsilon\nabla$.

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Let $V \in L^1(\mathbb{R}^3)$ be such that $\int |\hat{V}(p)|(1 + |p|^3) dp < \infty$.

Let ω_N satisfy

$$\mathrm{tr} |[x, \omega_N]| \leq CN\varepsilon, \quad \mathrm{tr} |[\varepsilon\nabla, \omega_N]| \leq CN\varepsilon.$$

Let $W_N \in L^1(\mathbb{R}^3 \times \mathbb{R}^3)$ be such that $\|W_N\|_{\mathcal{W}^{1,1}} \leq C$.

Then there exists $C > 0$ such that

$$|\mathrm{tr} e^{ip \cdot x + \varepsilon q \cdot \nabla} (\omega_{N,t} - \tilde{\omega}_{N,t})| \leq CN\varepsilon (1 + |p| + |q|)^2 \exp(C|t|),$$

$$\forall p, q \in \mathbb{R}^3, \forall t \in \mathbb{R}.$$

Strategy: trace norm convergence

Compare $\omega_{N,t}$ and $\tilde{\omega}_{N,t}$ via Gronwall inequality

Step 1.

$$i\varepsilon\partial_t(\omega_{N,t} - \tilde{\omega}_{N,t}) = [-\varepsilon^2\Delta, (\omega_{N,t} - \tilde{\omega}_{N,t})] + \dots$$

how to get rid of the kinetic term?

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Define a unitary operator \mathcal{U} ,

$$\begin{cases} i\varepsilon\partial_t\mathcal{U}(t) = h(t)\mathcal{U}(t), \\ \mathcal{U}(0) = 1. \end{cases}$$

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Then

$$\begin{aligned} i\varepsilon \partial_t \mathcal{U}^*(t) (\omega_{N,t} - \tilde{\omega}_{N,t}) \mathcal{U}(t) &= -\mathcal{U}^*(t) [h(t), \omega_{N,t} - \tilde{\omega}_{N,t}] \mathcal{U}(t) \\ &+ \mathcal{U}^*(t) ([h(t), \omega_{N,t} - \tilde{\omega}_{N,t}] + [V * \rho_t, \tilde{\omega}_{N,t}] - A_t) \mathcal{U}(t) \\ &= \mathcal{U}^*(t) ([V * (\rho_t - \tilde{\rho}_t), \tilde{\omega}_{N,t}] + [V * \tilde{\rho}_t, \tilde{\omega}_{N,t}] - A_t) \mathcal{U}(t). \end{aligned}$$

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where

$$B_t(x; y) = [V * \tilde{\rho}_t(x) - V * \tilde{\rho}_t(y) - \nabla(V * \tilde{\rho}_t) \left(\frac{x+y}{2} \right) \cdot (x-y)] \tilde{\omega}_{N,t}(x; y)$$

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Step 2.

Integrate in time and take the trace norm:

$$\begin{aligned} \|\omega_{N,t} - \tilde{\omega}_{N,t}\|_{\text{Tr}} &\leq \|\omega_{N,0} - \tilde{\omega}_{N,0}\|_{\text{Tr}} \\ &+ \frac{1}{\varepsilon} \int_0^t \|[V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}]\|_{\text{Tr}} ds \\ &+ \frac{1}{\varepsilon} \int_0^t \|B_s\|_{\text{Tr}} ds \end{aligned}$$

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Strategy

$$\frac{1}{\varepsilon} \int_0^t \|[V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}]\|_{\text{Tr}} ds$$

$$\|[V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}]\|_{\text{Tr}} \leq \|\rho_s - \tilde{\rho}_s\|_{L^1} \sup_z \|[V(z - \cdot), \tilde{\omega}_{N,s}]\|_{\text{Tr}}$$

Strategy

$$\frac{1}{\varepsilon} \int_0^t \| [V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}] \|_{\text{Tr}} ds$$

$$\| [V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}] \|_{\text{Tr}} \leq \| \rho_s - \tilde{\rho}_s \|_{L^1} \sup_z \| [V(z - \cdot), \tilde{\omega}_{N,s}] \|_{\text{Tr}}$$

heuristically

$$\begin{aligned} \| [V(z - \cdot), \tilde{\omega}_{N,s}] \|_{\text{Tr}} & \text{ " \leq " } \| [X, \tilde{\omega}_{N,s}] \|_{\text{Tr}} \text{ " = " } N\varepsilon \| \nabla \tilde{W}_{N,s} \|_{L^1_{x,v}} \\ & \leq CN\varepsilon \| \nabla W_{N,0} \|_{L^1} e^{C|s|} \end{aligned}$$

Strategy

$$\frac{1}{\varepsilon} \int_0^t \|[V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}]\|_{\text{Tr}} ds$$

$$\|[V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}]\|_{\text{Tr}} \leq \|\rho_s - \tilde{\rho}_s\|_{L^1} \sup_z \|[V(z - \cdot), \tilde{\omega}_{N,s}]\|_{\text{Tr}}$$

heuristically

$$\begin{aligned} \|[V(z - \cdot), \tilde{\omega}_{N,s}]\|_{\text{Tr}} & \text{ " } \leq \text{ " } \|[x, \tilde{\omega}_{N,s}]\|_{\text{Tr}} \text{ " } = \text{ " } N\varepsilon \|\nabla \tilde{W}_{N,s}\|_{L^1_{x,v}} \\ & \leq CN\varepsilon \|\nabla W_{N,0}\|_{L^1} e^{C|s|} \end{aligned}$$

$$\|\rho_s - \tilde{\rho}_s\|_{L^1} \leq \frac{1}{N} \|\omega_{N,s} - \tilde{\omega}_{N,s}\|_{\text{Tr}}$$

Strategy

$$\frac{1}{\varepsilon} \int_0^t \|[V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}]\|_{\text{Tr}} ds$$

$$\|[V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}]\|_{\text{Tr}} \leq \|\rho_s - \tilde{\rho}_s\|_{L^1} \sup_z \|[V(z - \cdot), \tilde{\omega}_{N,s}]\|_{\text{Tr}}$$

heuristically

$$\begin{aligned} \|[V(z - \cdot), \tilde{\omega}_{N,s}]\|_{\text{Tr}} & \text{ " } \leq \text{ " } \|[x, \tilde{\omega}_{N,s}]\|_{\text{Tr}} \text{ " } = \text{ " } N\varepsilon \|\nabla \tilde{W}_{N,s}\|_{L^1_{x,v}} \\ & \leq CN\varepsilon \|\nabla W_{N,0}\|_{L^1} e^{C|s|} \end{aligned}$$

$$\|\rho_s - \tilde{\rho}_s\|_{L^1} \leq \frac{1}{N} \|\omega_{N,s} - \tilde{\omega}_{N,s}\|_{\text{Tr}}$$

$$\begin{aligned} \|[V(z - \cdot), \tilde{\omega}_{N,s}]\|_{\text{Tr}} & \leq \|(1 - \varepsilon^2 \Delta)^{-1} (1 + x^2)^{-1}\|_{\text{HS}} \|(1 + x^2)(1 - \varepsilon^2 \Delta)[V(z - \cdot), \tilde{\omega}_{N,s}]\|_{\text{HS}} \\ & \leq C\sqrt{N} \|(1 + x^2)(1 - \varepsilon^2 \Delta)[V(z - \cdot), \tilde{\omega}_{N,s}]\|_{\text{HS}} \\ & \leq C \exp(C|s|) N\varepsilon [\|W_N\|_{H^1_4} + \varepsilon \|W_N\|_{H^2_4} + \varepsilon^2 \|W_N\|_{H^3_4} + \varepsilon^3 \|W_N\|_{H^4_4}] \end{aligned}$$

Strategy

$$\begin{aligned}\|\omega_{N,t} - \tilde{\omega}_{N,t}\|_{\text{Tr}} &\leq \|\omega_{N,0} - \tilde{\omega}_{N,0}\|_{\text{Tr}} \\ &+ \frac{1}{\varepsilon} \int_0^t \|[V * (\rho_s - \tilde{\rho}_s), \tilde{\omega}_{N,s}]\|_{\text{Tr}} ds \\ &+ \frac{1}{\varepsilon} \int_0^t \|B_s\|_{\text{Tr}} ds\end{aligned}$$

Strategy

$$\frac{1}{\varepsilon} \int_0^t \|B_s\|_{\text{Tr}} ds$$

with

$$B_t(x; y) = [V * \tilde{\rho}_t(x) - V * \tilde{\rho}_t(y) - \nabla(V * \tilde{\rho}_t) \left(\frac{x+y}{2} \right) \cdot (x-y)] \tilde{\omega}_{N,t}(x; y)$$

Strategy

$$\frac{1}{\varepsilon} \int_0^t \|B_s\|_{\text{Tr}} ds$$

with

$$B_t(x; y) = [V * \tilde{\rho}_t(x) - V * \tilde{\rho}_t(y) - \nabla(V * \tilde{\rho}_t) \left(\frac{x+y}{2} \right) \cdot (x-y)] \tilde{\omega}_{N,t}(x; y)$$

$$\| [x, [x, \tilde{\omega}_{N,s}]] \|_{\text{Tr}} = N \varepsilon^2 \| \nabla^2 \tilde{W}_s \|_{L^1_{x,v}}$$

Strategy

$$\frac{1}{\varepsilon} \int_0^t \|B_s\|_{\text{Tr}} ds$$

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$$\| [x, [x, \tilde{\omega}_{N,s}]] \|_{\text{Tr}} = N \varepsilon^2 \| \nabla^2 \tilde{W}_s \|_{L^1_{x,v}}$$

Strategy

$$\frac{1}{\varepsilon} \int_0^t \|B_s \tilde{\omega}_{N,s}\|_{\text{Tr}} ds$$

with

$$B_t(x; y) = V * \tilde{\rho}_t(x) - V * \tilde{\rho}_t(y) - \nabla(V * \tilde{\rho}_t) \left(\frac{x+y}{2} \right)$$

$$\| [X, [X, \tilde{\omega}_{N,s}]] \|_{\text{Tr}} = N \varepsilon^2 \| \nabla^2 \tilde{W}_s \|_{L^1_{x,v}}$$

Hence we conclude by Gronwall Lemma:

$$\begin{aligned} \|\omega_{N,t} - \tilde{\omega}_{N,t}\|_{\text{Tr}} &\leq C \int_0^t ds \|\omega_{N,s} - \tilde{\omega}_{N,s}\|_{\text{Tr}} \exp(C|s|) \\ &\quad + C N \varepsilon [\|W_N\|_{H^2_4} + \varepsilon \|W_N\|_{H^3_4} + \varepsilon^2 \|W_N\|_{H^4_4} + \varepsilon^3 \|W_N\|_{H^5_4}] \exp(C|s|) \end{aligned}$$